

# **CAPELLA SPACE**

# SAR PRODUCTS FORMAT SPECIFICATION





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### **DOCUMENT CHANGE LOG**

| Version | Date            | Change Description   |
|---------|-----------------|--|
| 1.0     | 10 April 2020   | Initial document version   |
| 1.1     | 6 May 2020      | Update STAC metadata to version 0.9.0  |
| 1.2     | 22 January 2021 | Added extended metadata fields, such as: Image:calibration, State:direction, CenterPixel:look_angle, Image:peak_nesz, Image:nesz_polynomial. Changed extended metadata fields, such as: Collect:id renamed to collect:collect_id, capella:billable_area. Updated definition of doppler centroid 2D polynomial. Updated SLC and GEO definition and description of internal calibration factor. Beta updated in Beta_nought for SLC products.  Reworked PRF object to TimeVaryingParameter |
| 1.3     | 25 May 2021     | New GEC image product type; New SICD product delivery format   |



|     |                      | Extended metadata field names 'scale_factor' and 'nesz_peak'. Added extended_metadata fields: Window:broadening_factor, Image:frequency_doppler_centroid_polynomial. Added capella:orbital_plane to STAC metadata.  |
|-----|----------------------|---|
| 1.4 | 18 Aug 2022          | Added capella:image_length & capella:image_width to the STAC catalog metadata. Clarified field descriptions for image product name start / stop time, sar:product_type and sar:orbital_plane in STAC catalog metadata, and product_type in extended metadata. |
| 1.5 | 26 January 2023      | Added proj:centroid, proj:shape, proj:transform, locale:datetime, locale:timezone, locale:time, & processing:software to the STAC catalog metadata. Added local_datetime and local_timezone to the extended metadata.   |
| 1.6 | 6 August 2024        | Added PFA-specific metadata.  |
| 1.7 | 25 September<br>2024 | Removed capella:product_category.   |



#### INTRODUCTION

Capella Space is an information services company that provides on-demand Earth observation imagery. Through a constellation of small satellites, Capella is providing easy access to frequent, timely and quality information affecting several of industries worldwide. Capella's very high-resolution synthetic aperture radar (SAR) satellites are matched with unparalleled infrastructure to deliver reliable global insights that sharpen our understanding of the changing world - improving decisions about commerce, conservation and well-being on Earth.

This document describes the format of the operational basic SAR imagery products generated by Capella's constellation of SAR satellites. Capella's SAR data product portfolio currently includes single look complex (SLC), geocoded ellipsoid corrected (GEC) and geocoded terrain corrected (GEO) image product types. SAR images for all imaging modes and product types are delivered in Capella's TIFF+JSON format. Furthermore, single look complex image data from spotlight and stripmap imaging modes are also made available in the Sensor Independent Complex Data (SICD) format.

This document presents in-depth information on how Capella's SAR imagery products are formatted, packaged, structured and how to access the metadata information. Figure 1 shows the processing steps applied to the raw SAR data to generate the single look complex and geocoded imagery products.



Figure 1: Processing steps to generate Capella's single look complex and geocoded imagery products.

## SINGLE LOOK COMPLEX (SLC)

SLC images are single-look, range-compressed and focused SAR data presented in the satellite image acquisition geometry of slant range and azimuth directions (Figure 2). The azimuth direction is along the flight path of the satellite. The slant range direction is perpendicular to the azimuth direction and follows from the satellite to the imaging targets on the ground. Image pixels are processed and projected to zero Doppler SAR coordinates.

SLC images contain both amplitude and phase information. Each image pixel is represented by a complex number with a real (Re) and imaginary (Im) component. SLC images have 32 bits for each pixel sample. The first 16 bits represent the real component of the complex value as a signed 16-bit integer (Int16) and the last 16 bits represent the imaginary component of the complex value as a signed 16-bit integer (Int16). This data type is also known as CInt16.



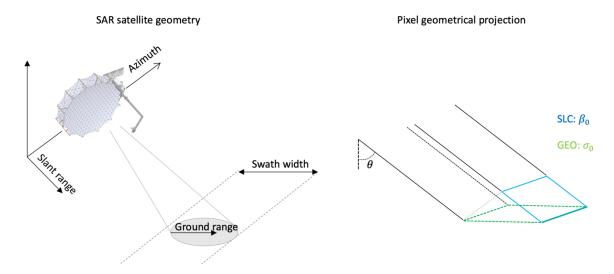


Figure 2: SAR satellite geometry and pixel projection in Capella's SLC and GEO products.

# **GEOCODED ELLIPSOID CORRECTED (GEC)**

GEC images are detected multi-looked dataset which has been geocoded and projected onto the WGS84 ellipsoid. Similar to the SLC image product type a GEC image is range-compressed and focused. The average scene center height is used to generate the GEC image product type and no terrain correction is performed. Consequently, GEC images are ideally suited for users who wish to analyze imagery over areas with significant topographic relief without any DEM correction applied. The pixel values and radiometric calibration process for the GEC image product type is the same as the GEO image described in the following sections below.

## **GEOCODED TERRAIN CORRECTED (GEO)**

GEO images are detected multi-looked dataset which has been geocoded and terrain-corrected using a Digital Elevation Model (DEM). Similar to the SLC image product type a GEO image is range-compressed and focused. The pixel values in the GEO images contain the radiometrically calibrated intensity in linear scale.

A Digital Elevation Model (DEM) is used to improve the geolocation accuracy beyond what is achievable with only considering the ellipsoid. The ground location accuracy for the GEO product depends on the accuracy of the DEM used for map projection and terrain correction.

Spotlight Ultra GEO images are multi-looked 5 times in the azimuth direction to enhance their radiometric resolution, which is a critical quality metric that describes the detection capability of a SAR system. It is a measure of an image's ability to display reflection differences among pixels.

Capella has implemented a multi-look technique obtained by splitting a long synthetic aperture into a set of sub-apertures and then combining them to generate the GEO image product type. For this purpose, five 0.25 m resolution SLC images are generated to make a Spotlight Ultra product.



### **CALIBRATION: BETA AND SIGMA NOUGHT**

The pixel value in GEC and GEO product types contains calibrated amplitude information, in *Sigma Nought* ( $\sigma^0$ ) [Ref 3]. In SLC data products, the calibrated pixel values are in represented in the slant range geometry, in *Beta Nought* (see Figure 2).

The  $\sigma^0$  values are obtained compensating *Beta Nought* ( $\beta^0$ ) for the incidence angle computed based on the ellipsoid. Therefore, the *Sigma Nought* can be defined as follows:

$$\sigma^0 = \beta^0 * \sin\theta$$

Where  $\theta$  is the incident angle estimated from the WGS84 ellipsoid on a simple ellipsoid and  $\beta^0$  is defined as:

$$\beta^0 = \beta/A^{\beta}$$

where  $\beta$  and  $A^{\beta}$  are radar backscattering and a reference area defined to be in the slant range plane, respectively (see Figure 2).

The aim of Sigma Nought is to minimize the differences in the image radiometry in images obtained from different incidence angles, ascending-descending geometries and/or opposite look directions becomes comparable and can be integrated to obtain derived change maps.

#### **SCALE FACTOR**

As part of Capella processing, a calibration factor is applied to take into account the internal calibration of the radar subsystems. The user shall apply only the "scale\_factor" (SC) reported in the extended metadata JSON sidecar file for any given SAR imagery product. SC is used to derive the radar brightness from the image pixel values and does not include a separate calibration component.

For SLC the expression for the radar brightness in logarithmic scale reads:

$$\sigma_{dB}^0 = 20 log_{10}(SC|DN_{slc}|\,)$$

Where  $|DN_{slc}|$  is the absolute value of the radar backscattering  $\beta$ .

Similarly, for GEC and GEO products:

$$\sigma_{dB}^0 = 20 log_{10} (SC DN_{gec/geo})$$

# SENSOR INDEPENDENT COMPLEX DATA (SICD) FORMAT

For SAR imagery products acquired in the Spot (spotlight) and Strip (stripmap) modes Capella delivers single look complex image data in the Sensor Independent Complex Data (SICD) format aligned with v1.2.1 of the SICD standard specification. SICD formatted imagery products are delivered as a single NITF format file (\*.ntf) which contains both the single look complex image data and relevant SAR metadata.



SICD is a U.S. national geospatial-intelligence (GEOINT) standard designed for the storage and dissemination of SAR single look complex (SLC) image data in a sensor-independent manner. The SICD standard leverages the well-established National Imagery Transmission Format (NITF) container format with customized raster segments and metadata tags specifically designed for the storage of SAR complex image products. Capella's SICD format complex image products are compliant with version 1.2.1 of the SICD standard published on 13 December 2018 (NGA.STND.0024-1\_1.2.1). Some Capella imagery products are generated with the backprojection algorithm which is supported in the SICD standard by setting ImageFormAlgo="OTHER".

#### **CAPELLA TIFF+JSON FORMAT**

Capella delivers SAR data for all image product modes (Spot | Site | Strip) and image product types (SLC | GEC | GEO) in a 3-file bundle package known as the Capella TIFF+JSON format. The Capella TIFF+JSON format bundle package includes one cloud-optimized GeoTIFF format image file along with two JSON metadata sidecar files (STAC & Extended). Each SAR imagery product delivered in Capella's TIFF+JSON format 3-file bundle package includes an Image Data File, a Catalog Metadata File, and an Extended Metadata File.

**Image Data File:** The Image Data File contains the raster file of processed SAR instrument data.

Naming Convention:

"EEEEEEE\_SSS\_MM\_PPP\_HH\_SSSSSSSSSSSSSSSS\_EEEEEEEEEEEE.tif"

**Catalog Metadata File:** The Catalog Metadata File contains information about the SAR data collection that allows users to easily search and find relevant data. This metadata is formatted as JSON following the Spatio Temporal Asset Catalog (STAC) specification [ref 2]. STAC simplifies the description of geospatial assets, the exploitation of both data fusion and time series analysis.

Naming Convention:

"EEEEEEE\_SSS\_MM\_PPP\_HH\_SSSSSSSSSSSSSSS\_EEEEEEEEEEEEEijson"

**Extended Metadata File:** The product extended metadata is a description of the data acquisition, calibration, noise, and product processing. It is formatted as JSON and included in the GeoTIFF TIFFTAG IMAGEDESCRIPTION TIFF Tag and a plain-text sidecar file.

Naming Convention:

"EEEEEEE\_SSS\_MM\_PPP\_HH\_SSSSSSSSSSSSSSSSSSEEEEEEEEEEEEeeeded.json"

| Tag     | Description              | Values  |
|---------|--------------------------|---|
| EEEEEEE | Company Name             | 'CAPELLA'   |
| SSS     | Satellite ID             | 'C01'=CAPELLA-1, 'C02'=CAPELLA-2, etc.  |
|         |                          | 'ARL' for aerial campaign data  |
| MM      | Mode of data acquisition | 'SP'=Spotlight, 'SM'=Stripmap, 'SL'=Sliding<br>Spotlight  |
| PPP     | Product type             | 'SLC' = Single Look Complex 'GEC' = Geocoded Ellipsoid Corrected 'GEO' = Geocoded Terrain Corrected |



| НН             | Polarization           | 'HH'=HH polarization, 'VH'=VH polarization, 'HV'=HV polarization, 'VV'=VV polarization. |
|----------------|------------------------|---|
| SSSSSSSSSSSSSS | Acquisition start time | In format YYYYMMDDTHHMMSS   |
| EEEEEEEEEEE    | Acquisition end time   | In format YYYYMMDDTHHMMSS   |
|                |                        | Actual integration time used to generate the SAR product is referenced the Catalog &    |
|                |                        | Extended metadata files.  |

### **CAPELLA TIFF+JSON - IMAGE DATA FILE**

Capella TIFF+JSON format image data files are provided as Cloud Optimized GeoTIFF (COG). A cloud optimized GeoTIFF is a regular GeoTIFF file, aimed at being hosted in a cloud computing environment, whose internal organization is friendly for consumption by clients issuing HTTP GET range request. It contains at its beginning the metadata of the full resolution imagery, followed by the optional presence of overview metadata, and finally the imagery itself.

More formally, the structure of such a file is:

- TIFF / BigTIFF signature
- Image File Directory of the full resolution image
- Values of TIFF tags that don't fit inline in the IFD directory, such as TileOffsets, TileByteCounts and GeoTIFF keys
- Tile content of full resolution image.

The GeoTIFF metadata structure for Capella products is:

| TIFF Tag                  | Code | Type  | Value    | Description   |
|---------------------------|------|-------|----------|---|
| ImageWidth                | 256  | LONG  | Variable | Number of pixels per line   |
| ImageLength               | 257  | LONG  | Variable | Number of lines in image  |
| Bits Per Sample           | 258  | SHORT | 32 or 16 | For SLC: 16 bits I and 16 bits Q<br>For GEO: 16 bits  |
| Compression               | 259  | SHORT | 1        | 1=No compression<br>8=Adobe DEFLATE   |
| PhotometricInterpretation | 262  | SHORT | 1        | Color space of the image. 1=minimum value is black.   |
| Image Description         | 270  | ASCII | Variable | Full extended metadata in JSON format, identical to the data contained in sidecar JSON file.            |
| SamplesPerPixel           | 277  | SHORT | 1        | Number of samples per pixel.  |
| PlanarConfiguration       | 284  | SHORT | 1        | Configuration in which the components (samples) of each pixel are stored. Always set to 1 (contiguous). |
| Software                  | 305  | ASCII | Variable | Processor name and version.   |
| DateTime                  | 306  | ASCII | Variable | Date and time of image creation in the format: YYYY:MM:DD HH:MM:SS                                      |



| Predictor          | 317   | SHORT            | 1 or 2   | A mathematical operator that is applied to the image data before an encoding scheme is applied.   |
|--------------------|-------|------------------|----------|---|
|                    |       |                  |          | <ul><li>1 = No prediction scheme used before coding.</li><li>2 = Horizontal differencing.</li></ul>   |
| TileWidth          | 322   | SHORT            | Variable | The tile width in pixels. This is the number of columns in each tile.   |
| TileLength         | 323   | SHORT            | Variable | The tile length (height) in pixels. This is the number of rows in each tile.  |
| TileOffsets        | 324   | Array of<br>LONG | Variable | For each tile, the byte offset of that tile, as compressed and stored on disk.  |
| TileByteCounts     | 325   | Array of<br>LONG | Variable | For each tile, the number of (compressed) bytes in that tile.   |
| SampleFormat       | 339   | SHORT            | 5 or 1   | Interpretation of pixel format. Set to 5 (complex signed integer) for SLC products and set to 1 (unsigned integer data) for GEO products  |
| ModelTiepointTag   | 33922 | DOUBLE           | Variable | This tag stores raster->model tiepoint pairs in the order   |
|                    |       |                  |          | ModelTiepointTag = (,I,J,K, X,Y,Z)  |
|                    |       |                  |          | where (I,J,K) is the point at location (I,J) in raster space with pixel-value K, and (X,Y,Z) is a vector in model space. In most cases the model space is only two-dimensional, in which case both K and Z should be set to zero; this third dimension is provided in anticipation of future support for 3D digital elevation models and vertical coordinate systems. |
| GeoKeyDirectoryTag | 34735 | SHORT            | Variable | Used in interchangeable GeoTIFF files.  |
| GeoDoubleParamsTag | 34736 | DOUBLE           | Variable | Used in interchangeasble GeoTIFF files.   |
| GeoAsciiParamsTag  | 34737 | ASCII            | Variable | Used in interchangeable GeoTIFF files.  |

### **CAPELLA TIFF+JSON - CATALOG METADATA**

The following table presents the fields of the STAC metadata included in the json metadata file.

| Element         | Description                           | Data Type | Unit |  |
|-----------------|---------------------------------------|-----------|------|--|
| Name            | •                                     |           |      |  |
| stac_version    | The STAC version the Item implements. | String    | -    |  |
|                 | Currently using the "0.9.0"           |           |      |  |
| stac_extensions | A list of extensions the Item         | String    | -    |  |
|                 | implements.                           |           |      |  |
|                 | E.g.: "sar","dtr"                     |           |      |  |
| id              | Filename is used as ID String         |           | -    |  |
| type            | Type of the GeoJSON Object. MUST      | String    | -    |  |
|                 | be set to "Feature"                   |           |      |  |



| bbox            | Bounding Box of the asset   | Numbers -     |
|-----------------|---|---------------|
|                 | represented by this item using either                             |               |
|                 | 2D or 3D geometries. The length of                                |               |
|                 | the array must be 2*n where n is the                              |               |
|                 | number of dimensions. The array                                   |               |
|                 | contains all axes of the southwesterly                            |               |
|                 | most extent followed by all axes of the                           |               |
|                 | northeasterly most extent specified in                            |               |
|                 | Longitude/Latitude or   |               |
|                 | Longitude/Latitude/Elevation based                                |               |
|                 | on <u>WGS 84</u> . When using 3D                                  |               |
|                 | geometries, the elevation of the                                  |               |
|                 | southwesterly most extent is the                                  |               |
|                 | minimum depth/height in meters and                                |               |
|                 | the elevation of the northeasterly most                           |               |
|                 | extent is the maximum. This field                                 |               |
|                 | enables more naive clients to easily                              |               |
|                 | index and search geospatially. STAC                               |               |
|                 | compliant APIs are required to                                    |               |
|                 | compute intersection operations with                              |               |
|                 | the item's geometry field, not its bbox.                          |               |
| geometry        | Defines the full footprint of the asset                           |               |
| geometry        | represented by this item, formatted                               |               |
|                 | according to RFC 7946, section 3.1.                               |               |
|                 | The footprint should be the default                               |               |
|                 | GeoJSON geometry, though  |               |
|                 | additional geometries can be                                      |               |
|                 | included. Coordinates are specified in                            |               |
|                 | Longitude/Latitude or   |               |
|                 | Longitude/Latitude/Elevation based                                |               |
|                 | on WGS 84.  |               |
| type            | Shape type "Polygon"  | String        |
| coordinates     | Longitude/Latitude or   | Number        |
|                 | Longitude/Latitude/Elevation based                                |               |
|                 | on <u>WGS 84</u> .  |               |
| properties      | A dictionary of additional metadata for                           |               |
|                 | the item.   |               |
| proj:centroid   | Coordinates representing the centroid                             | Centroid      |
|                 | of the Item (in lat/long)   | Object        |
| proj:shape      | Number of pixels in Y and X directions                            | Integer       |
|                 | for the default grid  |               |
| proj:transform  | The affine transformation coefficients                            | Number        |
|                 | for the default grid  |               |
| datetime        | Date and time of the acquisition                                  | String        |
|                 | E.g., "2019-08-22T06:54:11.00Z"                                   |               |
| start_datetime  | Start date and start time of the                                  | String        |
|                 | acquisition   | -             |
|                 | E.g., "2019-08-22T06:52:41.000000Z"                               |               |
| end_datetime    | End date and start time of the                                    | String        |
|                 | acquisition   | -             |
|                 | E.g., "2019-08-22T06:52:41.000000Z"                               |               |
| 1 1 1 1 1       | Local date and time of the acquisition.                           | String        |
| locale:datetime | ·   | <b>-</b>      |
| locale:datetime | E.g., "2021-02-   |               |
| locale:datetime | E.g., "2021-02-<br>2021T02:02:55.149182+0530"                     |               |
|                 | 2021T02:02:55.149182+0530"  | Strina        |
| locale:datetime | 2021T02:02:55.149182+0530"<br>Local time zone of the acquisition. | String        |
|                 | 2021T02:02:55.149182+0530"  | String String |



|  | E.g., "02:02:55.149182"  |                  |          |
|--|--|------------------|----------|
| platform   | Name of the platform   | String           |          |
| constellation                                      | Name of the platform   | String           |          |
| sar:instrument                                     | Name of the SAR instrument   | String           |          |
| sar:instrument_mode                                | Instrument mode.   | String           |          |
|  | E.g., "stripmap", "spotlight",   |                  |          |
|  | "sliding_spotlight"  |                  |          |
| sar:frequency_band                                 | SAR band.  | String           |          |
| , ,  | E.g., "X"  |                  |          |
| sar:center_frequency                               | Center frequency   | Number           | [GHz]    |
| sar:polarization                                   | Polarizations.   | String           |          |
|  | E.g., "HH", "HV", "VH", "VV"   |                  |          |
| sat:orbit_state                                    | Orbit state.   | String           |          |
| sar:product_type                                   | Imagery product type.  |                  |          |
|  | E.g.,"SLC", "GEO", "GEC", "SICD",  |                  |          |
|  | "SIDD", "CPHD"   |                  |          |
| sar:pixel_spacing_range                            | Pixel spacing in range.  | Number           |          |
|  | The pixel spacing is dependent on  |                  |          |
|  | what type of image is being  |                  |          |
|  | processed.   |                  |          |
|  | For aerial collects a 3D grid (for   |                  |          |
|  | backprojection processing) is defined.   |                  |          |
|  | The pixel spacing is the average   |                  |          |
|  | spacing between each grid point over   |                  |          |
|  | 100 pixels at the center of the image.   |                  |          |
|  | For satellite collects, the range  |                  |          |
|  | doppler geometry is used to calculate  |                  |          |
|  | the average spacing over 100 pixels at   |                  |          |
|  | the center of the image.   |                  |          |
| sar:pixel_spacing_azimuth                          | Pixel spacing in azimuth.  | Number           |          |
| sar:looks_range                                    | Number of looks in ground range.   | Number           |          |
| sar:looks_azimuth                                  | Number of looks in azimuth.  | Number           |          |
| sar:looks_equivalent_number                        | ENL (defined in a dedicated section  | Number           |          |
|  | below "Multi-looking strategy")  | NI I             |          |
| sar:resolution_range                               | Resolution in slant range  | Number           | r 1      |
| sar:resolution_azimuth                             | Resolution in azimuth  | Number           | [m]      |
| view:incidence_angle                               | Incidence angle. Angle is the angle between the vertical (normal) to the   | Number           | [degree  |
|  |  |                  |          |
|  |  |                  |          |
|  | intercepting surface and the line of   |                  |          |
|  |  |                  |          |
| capella:squint_angle                               | intercepting surface and the line of sight back to the satellite at the scene center.  | Number           | [degree  |
| capella:squint_angle                               | intercepting surface and the line of sight back to the satellite at the scene center.  Squint angle. It calculates the squint  | Number           | [degree  |
| capella:squint_angle                               | intercepting surface and the line of sight back to the satellite at the scene center.  Squint angle. It calculates the squint by looking at the angle between the  | Number           | [degree  |
| capella:squint_angle                               | intercepting surface and the line of sight back to the satellite at the scene center.  Squint angle. It calculates the squint by looking at the angle between the LOS vector and the velocity vector at  | Number           | [degree  |
| capella:squint_angle                               | intercepting surface and the line of sight back to the satellite at the scene center.  Squint angle. It calculates the squint by looking at the angle between the LOS vector and the velocity vector at the mid-point of the acquisition.  | Number           | [degree  |
| capella:squint_angle                               | intercepting surface and the line of sight back to the satellite at the scene center.  Squint angle. It calculates the squint by looking at the angle between the LOS vector and the velocity vector at the mid-point of the acquisition.  The LOS vector is the vector between  | Number           | [degree  |
| capella:squint_angle                               | intercepting surface and the line of sight back to the satellite at the scene center.  Squint angle. It calculates the squint by looking at the angle between the LOS vector and the velocity vector at the mid-point of the acquisition.  The LOS vector is the vector between the scene center pixel and the   | Number           | [degree  |
| capella:squint_angle                               | intercepting surface and the line of sight back to the satellite at the scene center.  Squint angle. It calculates the squint by looking at the angle between the LOS vector and the velocity vector at the mid-point of the acquisition.  The LOS vector is the vector between the scene center pixel and the platform position at the mid-point of   | Number           | [degree  |
| capella:squint_angle                               | intercepting surface and the line of sight back to the satellite at the scene center.  Squint angle. It calculates the squint by looking at the angle between the LOS vector and the velocity vector at the mid-point of the acquisition.  The LOS vector is the vector between the scene center pixel and the platform position at the mid-point of the acquisition. A 90 degree squint   | Number           | [degree  |
|  | intercepting surface and the line of sight back to the satellite at the scene center.  Squint angle. It calculates the squint by looking at the angle between the LOS vector and the velocity vector at the mid-point of the acquisition.  The LOS vector is the vector between the scene center pixel and the platform position at the mid-point of the acquisition. A 90 degree squint angle is considered to be no squint.  |                  | [degree  |
| sar:observation_direction                          | intercepting surface and the line of sight back to the satellite at the scene center.  Squint angle. It calculates the squint by looking at the angle between the LOS vector and the velocity vector at the mid-point of the acquisition.  The LOS vector is the vector between the scene center pixel and the platform position at the mid-point of the acquisition. A 90 degree squint angle is considered to be no squint.  "right" or "left" looking   | String           |          |
|  | intercepting surface and the line of sight back to the satellite at the scene center.  Squint angle. It calculates the squint by looking at the angle between the LOS vector and the velocity vector at the mid-point of the acquisition.  The LOS vector is the vector between the scene center pixel and the platform position at the mid-point of the acquisition. A 90 degree squint angle is considered to be no squint.  "right" or "left" looking  Number of squared meters used by                         |                  | [degree] |
| sar:observation_direction<br>capella:billable_area | intercepting surface and the line of sight back to the satellite at the scene center.  Squint angle. It calculates the squint by looking at the angle between the LOS vector and the velocity vector at the mid-point of the acquisition.  The LOS vector is the vector between the scene center pixel and the platform position at the mid-point of the acquisition. A 90 degree squint angle is considered to be no squint.  "right" or "left" looking  Number of squared meters used by Capella billing system. | String<br>Number |          |
| sar:observation_direction                          | intercepting surface and the line of sight back to the satellite at the scene center.  Squint angle. It calculates the squint by looking at the angle between the LOS vector and the velocity vector at the mid-point of the acquisition.  The LOS vector is the vector between the scene center pixel and the platform position at the mid-point of the acquisition. A 90 degree squint angle is considered to be no squint.  "right" or "left" looking  Number of squared meters used by                         | String           | [degree  |



| capella:orbital_plane | The orbital plane of the satellite that acquired the image. | Number |     |
|-----------------------|---|--------|-----|
|                       | E.g., 45, 53, 97  |        |     |
|                       | NA for aerial data.   |        |     |
| capella:image_length  | Length of image product using the                           | Number | [m] |
| , 3 = 3               | WGS84 ellipsoid projection with no                          |        |     |
|                       | terrain correction.   |        |     |
| capella:image_width   | Width of image product using the                            | Number | [m] |
| -                     | WGS84 ellipsoid projection with no                          |        |     |
|                       | terrain correction.   |        |     |
| processing:software   | The version of the processor that                           | String |     |
|                       | created this product.                                       | _      |     |
| links                 | List of link objects to resources and                       | String |     |
|                       | related URLs. A link with the rel set                       |        |     |
|                       | to self is strongly recommended.                            |        |     |
| assets                | Dictionary of asset objects that can be                     | String |     |
|                       | downloaded, each with a unique key.                         |        |     |
|                       | Some pre-defined keys are listed in                         |        |     |
|                       | the chapter ' <u>Asset types</u> '.                         |        |     |
| collection            | The id of the STAC Collection this Item                     | String |     |
|                       | references to (see collection relation                      |        |     |
|                       | type). This field is required if such a                     |        |     |
|                       | relation type is present. This field                        |        |     |
|                       | provides an easy way for a user to                          |        |     |
|                       | search for any Items that belong in a                       |        |     |
|                       | specified Collection.                                       |        |     |

### **CAPELLA TIFF+JSON - EXTENDED METADATA**

The Extended Metadata is provided in the JSON format as part of the image TIFF file in the TIFF tag "TIFFTAG\_IMAGEDESCRIPTION". It is also provided in a sidecar JSON file with the product.

Note: time and date fields are ISO8601 formatted and always in UTC.

#### **TOP LEVEL**

| Name                  | Туре      | Definition   |
|-----------------------|-----------|--|
| collect               | Collect   | See Collect table  |
| software_version      | string    | The version of the processor that created this product   |
| software_revision     | string    | An additional identifier for the software version  |
| product_type          | string    | Imagery product type.  Single Look Complex (SLC) Geocoded Terrain Corrected (GEO) Geocoded Ellipsoid Corrected (GEC) |
| processing_time       | timestamp | The approximate time of product creation   |
| processing_deployment | string    | A descriptor of the deployment of the processor used   |
| product_version       | string    | Describes the version of metadata used   |



# COLLECT

| Name             | Туре           | Definition                                |
|------------------|----------------|---|
| image            | Image          | See Image table                           |
| radar            | Radar          | See Radar table                           |
| state            | State          | See State table                           |
| pointing         | List[Pointing] | See Pointing table                        |
| transmit_antenna | Antenna        | See Antenna table                         |
| receive_antenna  | Antenna        | See Antenna table                         |
| platform         | string         | The platform of the acquisition           |
| mode             | string         | The acquisition mode of the radar. One of |
|                  |                | • stripmap                                |
|                  |                | <ul> <li>sliding_spotlight</li> </ul>     |
|                  |                | <ul> <li>spotlight</li> </ul>             |
| collect_id       | string         | A unique identifier for the collect       |
| start_timestamp  | timestamp      | Timestamp for the start of the collection |
| stop_timestamp   | timestamp      | Timestamp for the end of the collection   |
| local_datetime   | timestamp      | Local date and time of the acquisition.   |
| local_timezone   | string         | Local time zone of the acquisition.       |

# **IMAGE**

| Name                 | Туре        | Definition   |
|----------------------|-------------|--|
| data_type            | string      | The data type of the image   |
|                      |             | • UInt16   |
|                      |             | • CInt16   |
| rows                 | int         | The number of rows in the image  |
| columns              | int         | The number of columns in the image   |
| pixel_spacing_row    | float       | The meters between samples in the row direction at the center of the image.    |
| pixel_spacing_column | float       | The meters between samples in the column direction at the center of the image. |
| range_resolution     | float       | The resolution in the slant range direction.                                   |
| azimuth_resolution   | float       | The resolution in the azimuth direction.                                       |
| scale_factor         | float       | The value to multiply the TIFF values by to recover the true science data      |
| center_pixel         | CenterPixel | Describes various properties about the scene center pixel                      |



| algorithm                        | string        | The algorithm used to transform the raw data to SLC  |
|----------------------------------|---------------|--|
|                                  |               | <ul> <li>backprojection</li> </ul>   |
|                                  |               | <ul> <li>omegak</li> </ul>   |
|                                  |               | • rda  |
| range_window                     | Window        | The window applied in the range direction  |
| azimuth_window                   | Window        | The window applied in the azimuth direction  |
| processed_azimuth_bandwidth      | float         | The processed azimuth bandwidth in<br>Hz   |
| image_geometry                   | ImageGeometry | The image geometry of this image   |
| azimuth_looks                    | float         | The number of looks in the azimuth direction   |
| range_looks                      | float         | The number of looks in the range direction   |
| enl                              | float         | The theoretical ENL of the image   |
| azimuth_beam_pattern_corrected   | bool          | True if azimuth beam pattern correction was applied  |
| elevation_beam_pattern_corrected | bool          | True if the elevation beam pattern correction was applied  |
| radiometry                       | string        | • beta   |
|                                  |               | <ul><li>beta_nought</li></ul>  |
|                                  |               | <ul><li>sigma_nought</li></ul>   |
| calibration                      | string        | <ul> <li>none (no calibration applied)</li> </ul>  |
|                                  |               | <ul> <li>limited (calibration applied,<br/>with no telemetry)</li> </ul>   |
|                                  |               | <ul> <li>partial (calibration applied,<br/>with partial telemetry)</li> </ul>  |
|                                  |               | <ul> <li>full (calibration applied, with all<br/>telemetry)</li> </ul>   |
| calibration_id                   | string        | Version of the calibration applied to the data products. Format of string is:  |
|                                  |               | <platform>/<start_datetime>-<br/><optional_end_datetime>/<version></version></optional_end_datetime></start_datetime></platform> |
|                                  |               | For example, the preliminary calibration for products from Capella-2 satellite is:   |
|                                  |               | capella-2/2020-09-10T00:00:00Z_/1  |
| nesz_peak                        | float         | Noise equivalent sigma-zero (NESZ) in<br>dB at the peak in the antenna gain<br>pattern (e.g. the minimum NESZ in the<br>image)   |



| nesz_polynomial                       | Polynomial | A 1D polynomial of Noise equivalent sigma-zero (NESZ) in dB, as a function of absolute range in meters.   |
|---------------------------------------|------------|---|
| frequency_doppler_centroid_polynomial | Polynomial | A 2D polynomial mapping range and azimuth time to doppler centroid frequency in Hz. Notice that the range dependence of the DC polynomial uses range distance. The azimuth variable is seconds since first_line_time. |

If range\_looks or azimuth\_looks are greater than 1, the following fields are also included:

| Name                   | Туре   | Definition                                    |
|------------------------|--------|---|
| multilooking_algorithm | string | A description of the multilook algorithm used |
|                        |        | • boxcar                                      |
|                        |        | <ul> <li>traditional</li> </ul>               |
|                        |        | • improved                                    |

### **IMAGEGEOMETRY**

| Name | Туре   | Definition                               |
|------|--------|--|
| type | string | Describes the type of the image geometry |
|      |        | <ul><li>slant_plane</li></ul>            |
|      |        | • surface                                |
|      |        | <ul> <li>geotransform</li> </ul>         |
|      |        | • pfa                                    |

For type==geotransform, the following additional fields are specified:

| Name              | Туре             | Definition  |
|-------------------|------------------|---|
| geotransform      | List             | 6-element affine transform<br>line/pixel → lat/lon                      |
| coordinate_system | CoordinateSystem | The coordinate system that the 6-element affine transform transforms to |

For type==pfa, the following additional fields are specified

| Name                          | Туре        | Definition   |
|-------------------------------|-------------|--|
| scene_reference_point_row_col | List[int]   | The row and column at the scene reference point in units of pixels |
| scene_reference_point_ecef    | List[float] | The scene reference point in ECEF meters                           |
| row_sample_spacing            | float       | The sample spacing in meters in the row direction                  |



| col_sample_spacing                          | float            | The samples spacing in meters in the column direction   |
|---|------------------|---|
| row_direction                               | List[float]      | A unit vector in ECEF indicating the row direction  |
| col_direction                               | List[float]      | A unit vector in ECEF indicating the column direction   |
| slant_plane_normal                          | List[float]      | A 3D unit vector in ECEF describing the direction normal to the slant plane   |
| ground_plane_normal                         | List[float]      | A 3D unit vector in ECEF describing the direction normal to the ground plane  |
| polar_angle_polynomial                      | Polynomial       | A 1D polynomial mapping seconds since collect_start to polar angle in radians   |
| spatial_frequency_scale_factor_polynomial   | Polynomial       | A 1D polynomial mapping polar angle in radians to Spatial Frequency Scale Factor. Used to scale RF frequency to aperture spatial frequency. |
| >antenna_reference_point_polynomial         | Polynomial       | 3 1D polynomials in X, Y, Z (ECEF) mapping seconds since collect_start to the antenna reference point (in meters)                           |
| velocity_antenna_reference_point_polynomial | Polynomial       | 3 1D polynomial in X, Y, Z (ECEF) mapping seconds since collect_start to the velocity of the antenna reference point (in meters/second)     |
| center_of_aperture                          | CenterOfAperture | See CenterOfAperture below  |

For type==slant\_plane, the following additional fields are specified:

| Name                        | Туре       | Definition   |
|-----------------------------|------------|--|
| doppler_centroid_polynomial | Polynomial | A 2D polynomial mapping range and azimuth time to doppler centroid frequency in Hz used to compute the image geometry. Notice that the range dependence of the DC polynomial uses range distance. The azimuth variable is seconds since first_line_time. |
| first_line_time             | timestamp  | The timestamp of the first line  |
| delta_line_time             | float      | The time difference between successive lines in seconds  |
| range_to_first_sample       | float      | The slant range distance to the first sample in meters   |
| delta_range_sample          | float      | The slant range delta distance between each sample in meters   |

For type==surface, the following additional fields are specified:

| Name         | Туре   | Definition                        |  |
|--------------|--------|-----------------------------------|--|
| surface_type | string | Describes the type of the surface |  |
|              |        | • affine                          |  |
|              |        | <ul> <li>equispaced</li> </ul>    |  |



| coordinate_system | CoordinateSystem | Description of the coordinate system of the surface coordinates |
|-------------------|------------------|---|
| Z                 | DEM              | The DEM used to compute the z dimension of the surface          |

For surface\_type==affine, the following extra fields are included:

| Name         | Туре | Definition                 |
|--------------|------|----------------------------|
| geotransform | List | 6-element affine transform |

For surface\_type==equispaced, the following fields are also specified:

| Name | Туре  | Definition                                |  |
|------|-------|---|--|
| х0   | float | The initial coordinate in the X direction |  |
| dx   | float | The spacing the X direction               |  |
| у0   | float | The initial coordinate in the Y direction |  |
| dy   | float | The spacing in the Y direction            |  |

### **CENTEROFAPERTURE**

| Name                             | Туре        | Definition   |
|----------------------------------|-------------|--|
| time                             | float       | Seconds since collect_start to the time of center of aperture  |
| antenna_reference_point          | List[float] | A 3-vector in ECEF meters describing the antenna reference point at center of aperture time                            |
| velocity_antenna_reference_point | List[float] | A 3-vector in ECEF meters/second describing the velocity of the antenna reference point at the center of aperture time |
| polar_angle                      | float       | The polar angle in radians at the center of aperture time  |
| spatial_frequency_scale_factor   | float       | The Spatial Frequency Scale Factor at the center of aperture time  |

### **RADAR**

| Name                    | Туре                       | Definition                                      |
|-------------------------|----------------------------|---|
| transmit_polarization   | string                     | The transmit polarization of the radar          |
| receive_polarization    | string                     | The receive polarization of the radar           |
| rank                    | int                        | The number of PRIs between transmit and receive |
| center_frequency        | float                      | The center frequency of the radar (Hz)          |
| time_varying_parameters | List[TimeVaryingParameter] | A list of TimeVaryingParameter objects          |
| pointing                | string                     | <ul><li>right</li><li>left</li></ul>            |
| sampling_frequency      | float                      | The sampling frequency of the ADC in Hz         |



#### **STATE**

| Name              | Туре              | Definition  |
|-------------------|-------------------|---|
| coordinate_system | CoordinateSystem  | A CoordinateSystem object describing the spatial coordinates of the orbit |
| state_vectors     | List[StateVector] | A list of StateVectors describing the platform position and velocity      |
| source            | string            | Orbit product used in processing  |
| direction         | string            | • ascending   |
|                   |                   | • descending  |
|                   |                   | <ul> <li>null (if not applicable)</li> </ul>                              |

### **STATEVECTOR**

| Name     | Туре        | Definition   |
|----------|-------------|--|
| time     | timestamp   | The timestamp of the measurement time of the state vector  |
| position | List[float] | A list of 3 floats (x,y,z) describing position in the orbit coordinate system                            |
| velocity | List[float] | A list of 3 floats (vx, vy, vz) describing the velocity of the platform in the orbit's coordinate system |

### **POINTING**

| Name     | Туре        | Definition   |
|----------|-------------|--|
| time     | timestamp   | The timestamp of the attitude measurement  |
| attitude | List[float] | A list of 4 floats (w, x, y, z) describing the rotation from the coordinate_system frame to the antenna frame as a quaternion, where w is the scale. The antenna frame is defined as: Z is boresight, and X and Y are the reference azimuth and elevation directions respectively. |

### **ANTENNA**

| Name                | Туре       | Definition  |
|---------------------|------------|---|
| azimuth_beamwidth   | float      | The 3dBi azimuth beamwidth in radians   |
| elevation_beamwidth | float      | The 3dBi elevation beamwidth in radians   |
| gain                | float      | The one way gain of the antenna in dBi  |
| beam_pattern        | Polynomial | A 2D polynomial that gives normalized (maximum 0dBi) one way<br>beam pattern as a function of offboresight angle in elevation and<br>azimuth in dBi |



### **COORDINATESYSTEM**

| Name | Туре   | Definition                              |
|------|--------|---|
| type | string | The type of coordinate system, one of   |
|      |        | • ecef                                  |
|      |        | <ul> <li>local_tangent_plane</li> </ul> |
|      |        | • wkt                                   |

If type==local\_tangent\_plane, the following extra fields are included:

| Name      | Туре        | Definition  |
|-----------|-------------|---|
| transform | List[float] | A list of 16 floats describing a 3D homogeneous transformation matrix from ECEF to the local tangent plane coordinate system. |

If type==wkt, the following extra fields are included:

| Name | Туре   | Definition   |
|------|--------|--|
| wkt  | string | A string representation of the WKT describing the coordinate frame |

### **WINDOW**

| Name              | Туре   | Definition   |
|-------------------|--------|--|
| name              | string | The name of the Window   |
| parameters        | object | A free-from object describing the parameters for the window raised cosine taylor |
| broadening_factor | float  | The impulse response broadening factor associated with the Window                |

#### **POLYNOMIAL**

| Name         | Туре        | Definition  |  |
|--------------|-------------|---|--|
| type         | string      | The type of polynomial  |  |
|              |             | • standard  |  |
|              |             | <ul> <li>chebyshev</li> </ul>   |  |
|              |             | • legendre  |  |
| dimension    | int         | The dimension of the polynomial   |  |
| degree       | float       | Max degree of coefficient   |  |
| coefficients | List[float] | Array of coefficients ordered so that the coefficient of the term of multi-<br>degree (i_0, i_1, i_n) is contained at index (0, 1,, n) where n is the<br>dimension above. The size of the array in each dimension is degree +<br>1. |  |



## **TimeVaryingParameter**

| Name             | Туре            | Definition  |
|------------------|-----------------|---|
| start_timestamps | List[timestamp] | A list of timestamps indicating when the specified PRF becomes active |
| prf              | float           | The PRF in Hz   |
| pulse_bandwidth  | float           | The bandwidth of the transmitted pulse in Hz                          |
| pulse_duration   | float           | The time duration of the transmitted pulse in seconds                 |

#### **CENTERPIXEL**

| Name            | Туре        | Definition  |
|-----------------|-------------|---|
| incidence_angle | float       | The incidence angle in degrees                              |
| squint_angle    | float       | The squint angle in degrees                                 |
| look_angle      | float       | The look ange in degrees                                    |
| target_position | List[float] | The ECEF coordinates of the center pixel                    |
| center_time     | timestamp   | The timestamp of when the antenna center acquired the pixel |

#### **Terrain Models**

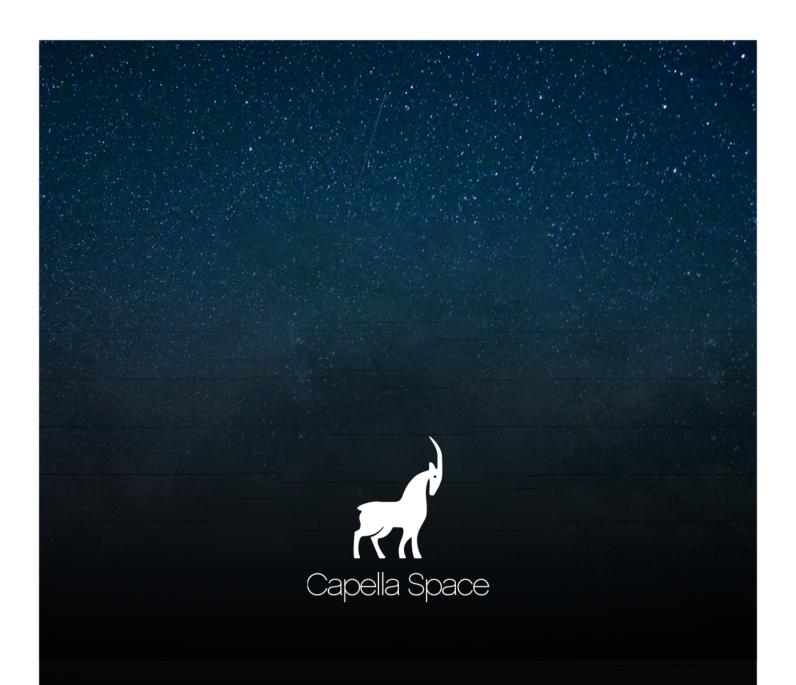
For SLC product type, we include the terrain model used for focusing during backprojection. For GEC and GEO products, we include the terrain model used for focusing during backprojection and for reprojection during orthorectification.

| Name | Туре   | Definition   |
|------|--------|--|
| link | string | An internal identifier for the terrain model and the link to the source.                   |
|      |        | E.g., "WhiteboxFilter[AW3D30v2012,8,50]+https://www.eorc.jaxa.jp/ALOS/en/aw3d30/index.htm" |
| namo | string | An internal identifier for the terrain model used. E.g.,                                   |
| name | sung   | "WhiteboxFilter[AW3D30v2012,8,50]"   |



# **REFERENCES**

| Ref # | Document Title  |
|-------|---|
| Ref 1 | Capella Space - SAR Imagery Products Guide  |
| Ref 2 | Spatio Temporal Asset Catalog: <a href="https://stacspec.org/">https://stacspec.org/</a>              |
| Ref 3 | D. Small, "Flattening Gamma: Radiometric Terrain Correction for SAR Imagery," in IEEE Transactions on |
|       | Geoscience and Remote Sensing, vol. 49, no. 8, pp. 3081-3093, Aug. 2011.                              |



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